# AUBO-i10

# **i** SERIES

# **COLLABORATIVE ROBOT**



**10KG** 

**Payload** 



38.5KG

Weight



±0.03mm Repeatability



1350mm

Reach

- ✓ The AUBO-i10 collaborative robot has a maximum working radius of 1350mm,
- ✓ A payload capacity of 10kg, and boasts a repeat positioning accuracy of ±0.03mm.
- ✓ It offers a high payload and a long working radius.

### **Application Fields**

3C electronics, automotive, new energy, semiconductors, mechanical processing, hardware home appliances, kitchen and bathroom sanitary ware, medical health, scientific research and education, catering, new retail, daily chemicals, logistics.



### **Product Advantages**

- More Accurate Positioning The repeatability and power-on positioning accuracy have been further improved, the maximum collision force value has been reduced, and millisecond-level system response speed ensures accurate positioning, resulting in a smoother operation trajectory.
- Faster Speed Working speed has been increased by 10%-20%. The 6-axis robotic arm operates efficiently, which significantly improves work efficiency.
- Stronger Functionality An open system platform with integrated 485 communication at the end of the arm has been adopted, and functions such as end-of-arm tool drag-and-drop teaching are added. It supports high-current power supply and can directly establish communication with a wider variety of end effectors, vision systems, mobile and other peripheral equipment, making the system more flexible and convenient.
- Superior Safety The product has passed multiple professional certifications, is stable and reliable, with improved collision detection sensitivity, and does not require safety barriers, making human-robot collaboration safer.















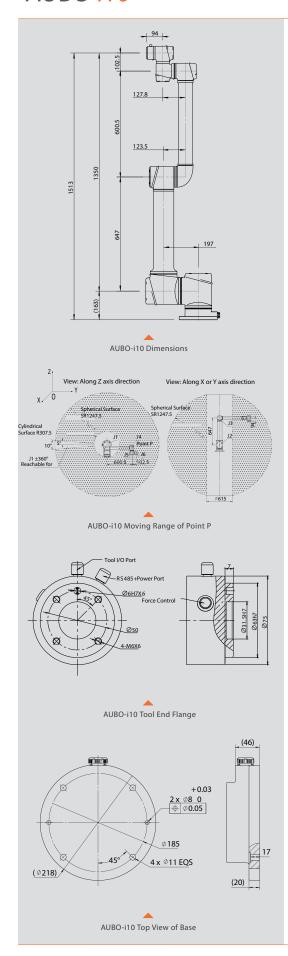








## AUBO i10



### Robot

Degrees of Freedom	6
Reach (mm)	1350
Payload (kg)	10
Weight (kg)	38.5
Mounting Surface Diameter (mm)	Ø220
Repeatability (mm)	±0.03
Linear Velocity (m/s)	≪4.0
Average Power(W)	500
Peak Power (W)	2000
Ambient Temperature ( $^{\circ}$ C)	0-50
Ambient Humidity	90%RH (Non-condensing)
Installation Orientation	Any ceiling, Floor, Wall
IP Classification	IP54
ISO 14644-1 Cleanliness Class	5



#### Axis Movement

	Working Range (°)	Maximum Speed (°/s)
joint 1	±360	178
joint 2	±360	178
joint 3	±167	223
joint 4	±360	237
joint 5	±360	237
joint 6	±360	237

<sup>\*</sup>Each joint has the ability of  $\pm 360$ ', but limited by the application scenario, part of the joints may not be reached.

### Control Box

Model	AUBO-CB-M
Size (L*W*H)	380mm*350mm*265mm
Weight	15 kg
Cable Connecting Robot	5 m (customizable, up to 8m)
Cable Connecting Pendant	4m
Cable Connecting Power	5m
Communication	Ethernet、ModBus-RTU/TCP、Profinet (optional)
Interface	SDK(support C/C++/C#/Lua/Python), support ROS, API
Power Supply	100-240VAC,50-60Hz
IP Classification	IP43

#### Control Box I/O, Tool I/O

Control Box	/0, 10011/0	Control Box	Tool
I/O Port	Digital In	16 (general) /16 (safe)	4(optional)
	Digital Out	16 (general) /16 (safe)	4(optional)
	Analog In	4	2
	Analog Out	4	-
I/O Power	Output Voltage	24V	0V/12V/24V
	Output Current	3A max	0.8A

### **Teach Pendant**

Model	AUBO-TP
Dimensions	322*236*45.2mm (Excluding E-Stop Button)
Weight	2.56kg (Including Cable)
IP Classification	IP43
Colors	Orange + black



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